

AE 429 - Aircraft Performance and Flight Mechanics

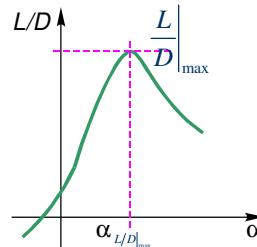
Steady Flight

Aerodynamic efficiency

- Lift/drag ratio is a measure of aerodynamic efficiency
 - It indicates the ability to produce lift without generating excessive drag

MAX L/D
0.3-0.4
12.8
26

VEHICLE
GEMINI
T-38
SAILPLANE



- Character of drag

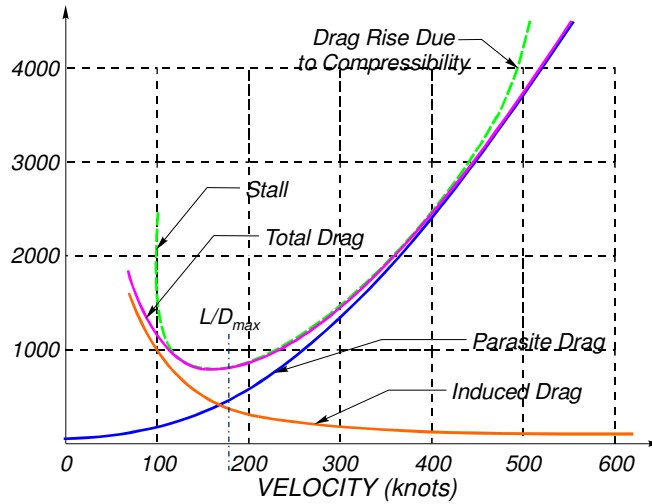
$$C_L = \frac{2L}{\rho V^2 S} = \frac{2W}{\rho V^2 S}; \quad C_D = C_{D_0} + \frac{C_L^2}{\pi e AR} = C_{D_0} + KC_L^2 = C_{D_0} + \frac{4W^2}{\rho^2 V^4 S^2 \pi e AR}$$

$$D = \frac{1}{2} \rho V^2 S C_{D_0} + \frac{2W^2}{\rho V^2 S \pi e AR} = \frac{1}{2} \rho V^2 S C_{D_0} + \frac{1}{2} \rho V^2 S K C_L^2$$

Zero lift drag Drag due to lift

Aerodynamic efficiency

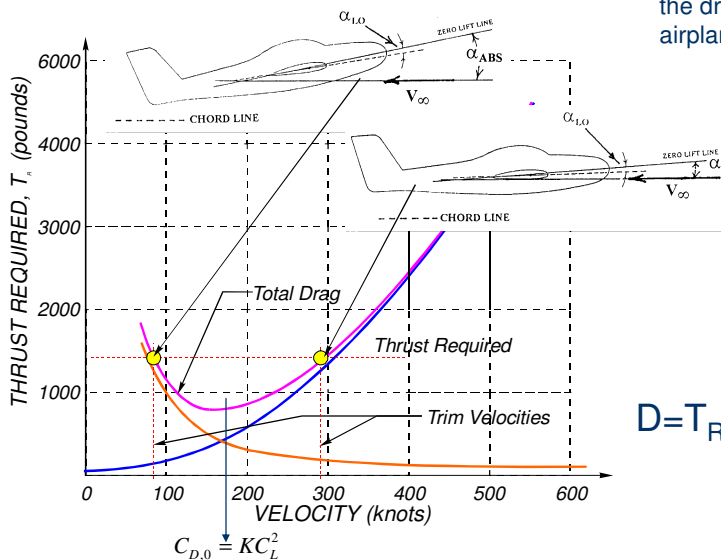
Parasite and induced drag



Aerodynamic efficiency

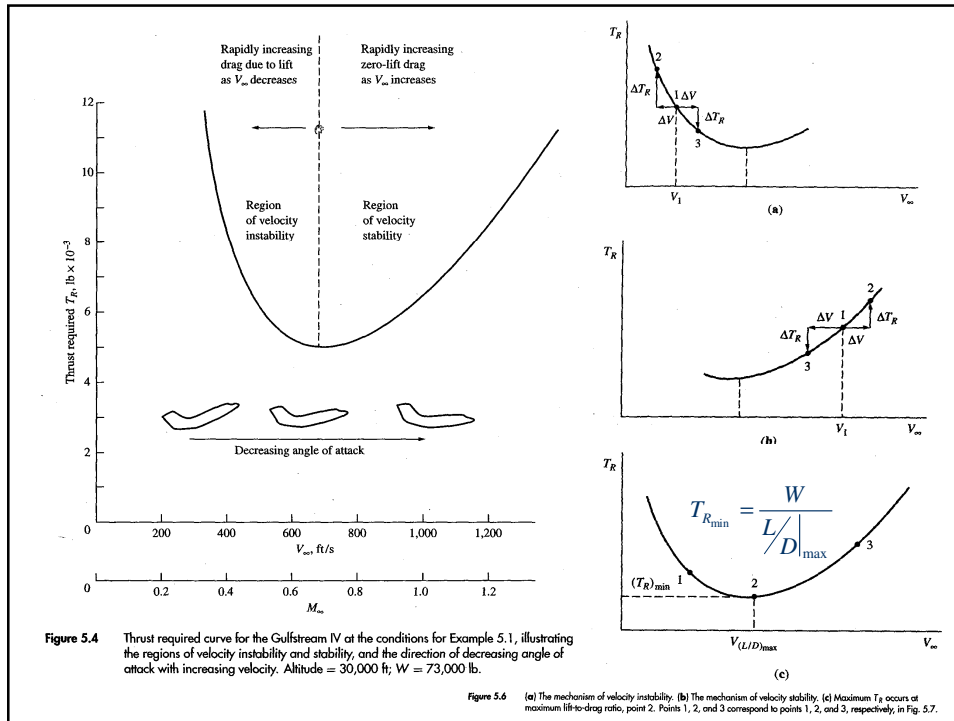
In level flight, $D = \text{thrust required } T_R$

To maintain certain speed and altitude, enough thrust must be generated to overcome the drag and to keep the airplane going.



**Thrust
Required
Curve**

$$D = T_R = f(h, V, W)$$



$$\text{Drag} = T_R$$

$$D = qSC_D = \frac{1}{2} \rho V^2 S [C_{D_0} + KC_L^2] = \frac{1}{2} \rho V^2 S \left[C_{D_0} + \frac{4KW^2}{(\rho V^2 S)^2} \right]$$

$$\text{Since for } L=W \quad C_L = \frac{2W}{(\rho V^2 S)}$$

$$D = \frac{1}{2} \rho V^2 S C_{D_0} + \frac{2SK}{\rho V^2} \left(\frac{W}{S} \right)^2 = f(h, V, W)$$

$$K = \frac{1}{e\pi AR}$$

Important parameters:

Thrust to Weight ratio T_R/W
 Wing loading W/S ,
 Polar drag (C_{D_0} and K)

Aerodynamic efficiency

- Relationship of C_{D0} and C_{Di} for L/D_{max}

$$T_R = C_{D0} q_\infty S + \frac{W^2}{q_\infty S \pi e AR}$$

- Differentiating with respect to q_∞ : $\frac{dT_R}{dq_\infty} = C_{D0} S - \frac{W^2}{q_\infty^2 S \pi e AR} = 0$

- Solving for C_{D0} $C_{D0} = \frac{W^2}{q_\infty^2 S^2 \pi e AR} = \frac{KW^2}{q_\infty^2 S^2}$

- And observing that $\frac{W^2}{q_\infty^2 S^2} = \left(\frac{W}{q_\infty S}\right)^2 = C_L^2$

- Thus, at max L/D

$$C_{D0} = \frac{C_L^2}{\pi e AR} = C_{Di}$$

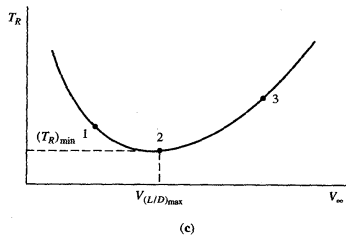


Figure 5.6 (a) The mechanism of velocity instability. (b) The mechanism of velocity stability. (c) Maximum T_R occurs at maximum lift-to-drag ratio, point 2. Points 1, 2, and 3 correspond to points 1, 2, and 3, respectively, in Fig. 5.7.

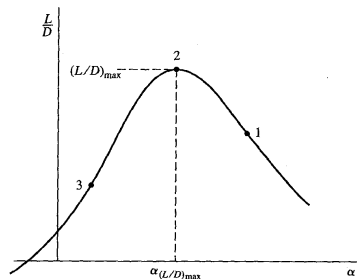


Figure 5.7 Schematic of the variation of lift-to-drag ratio for a given airplane as a function of angle of attack. Points 1, 3, and 3 correspond to points 1, 2, and 3, respectively, in Fig. 5.6c.

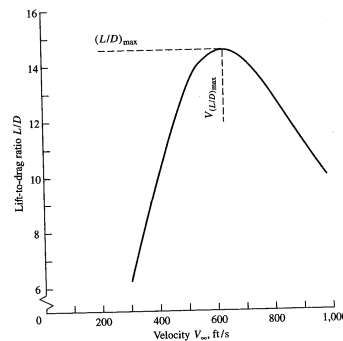


Figure 5.8 Variation of L/D with velocity for the Gulfstream IV at the conditions for Example 5.1. Altitude = 30,000 ft; $W = 73,000$ lb.

Equation (5.12) can be used to find the flight velocities for a given value of T_R . Writing Eq. (5.12) in terms of the dynamic pressure $q_\infty = \frac{1}{2}\rho_\infty V_\infty^2$ and noting that $D = T_R$, we obtain

$$T_R = q_\infty S C_{D,0} + \frac{K S}{q_\infty} \left(\frac{W}{S}\right)^2 \quad [5.13]$$

Multiplying Eq. (5.13) by q_∞ , and rearranging, we have

$$q_\infty^2 S C_{D,0} - q_\infty T_R + K S \left(\frac{W}{S}\right)^2 = 0 \quad [5.14]$$

Note that, being a quadratic equation in q_∞ , Eq. (5.14) yields two roots, that is, two solutions for q_∞ . Solving Eq. (5.14) for q_∞ by using the quadratic formula results in

$$\begin{aligned} q_\infty &= \frac{T_R \pm \sqrt{T_R^2 - 4S C_{D,0} K (W/S)^2}}{2S C_{D,0}} \quad [5.15] \\ &= \frac{T_R/S \pm \sqrt{(T_R/S)^2 - 4C_{D,0} K (W/S)^2}}{2C_{D,0}} \end{aligned}$$

By replacing q_∞ with $\frac{1}{2}\rho_\infty V_\infty^2$, Eq. (5.15) becomes

$$V_\infty^2 = \frac{T_R/S \pm \sqrt{(T_R/S)^2 - 4C_{D,0} K (W/S)^2}}{\rho_\infty C_{D,0}} \quad [5.16]$$

The parameter T_R/S appears in Eq. (5.16); analogous to the wing loading W/S , the quantity T_R/S is sometimes called the *thrust loading*. However, in the hierarchy of parameters important to airplane performance, T_R/S is not quite as fundamental as the wing loading W/S or the thrust-to-weight ratio T_R/W (as will be discussed in the next section). Indeed, T_R/S is simply a combination of T_R/W and W/S via

$$\frac{T_R}{S} = \frac{T_R}{W} \frac{W}{S} \quad [5.17]$$

Substituting Eq. (5.17) into (5.16) and taking the square root, we have our final expression for velocity:

$$V_\infty = \left[\frac{(T_R/W)(W/S) \pm (W/S)\sqrt{(T_R/W)^2 - 4C_{D,0}K}}{\rho_\infty C_{D,0}} \right]^{1/2} \quad [5.18]$$

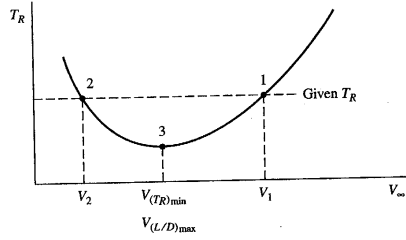


Figure 5.9 At a given T_R larger than the minimum value, there are two corresponding velocities, the low velocity V_2 and the high velocity V_1 .

When the discriminant in Eq. (5.18) equals zero, then only one solution for V_∞ is obtained. This corresponds to point 3 in Fig. 5.9, namely, the point of minimum T_R . That is, in Eq. (5.18) when

$$\left(\frac{T_R}{W}\right)^2 - 4C_{D,0}K = 0 \quad [5.19]$$

then the velocity obtained from Eq. (5.18) is

$$V_{(T_R)\min} = \left[\frac{1}{\rho_\infty C_{D,0}} \left(\frac{T_R}{W}\right)_{\min} \frac{W}{S} \right]^{1/2} \quad [5.20]$$

The value of $(T_R/W)_{\min}$ is given by Eq. (5.19) as

$$\left(\frac{T_R}{W}\right)_{\min}^2 = 4C_{D,0}K$$

or

$$\left(\frac{T_R}{W}\right)_{\min} = \sqrt{4C_{D,0}K} \quad [5.21]$$

Substituting Eq. (5.21) into Eq. (5.20), we have

$$V_{(T_R)\min} = \left(\frac{\sqrt{4C_{D,0}K} W}{\rho_\infty C_{D,0} S} \right)^{1/2}$$

or

$$V_{(T_R)\min} = V_{(L/D)\max} = \left(\frac{2}{\rho_\infty} \sqrt{\frac{K}{C_{D,0}}} \frac{W}{S} \right)^{1/2} \quad [5.22]$$

In Eq. (5.22), by stating that $V_{(T_R)\min} = V_{(L/D)\max}$, we are recalling that the velocity for minimum T_R is also the velocity for maximum L/D , as shown in Fig. 5.6. Indeed, since $T_R = D$ and $L = W$ for steady, level flight, Eq. (5.21) can be written as

$$\left(\frac{D}{L}\right)_{\min} = \sqrt{4C_{D,0}K} \quad [5.23]$$

Since the minimum value of D/L is the reciprocal of the maximum value of L/D , then Eq. (5.23) becomes

$$\left(\frac{L}{D}\right)_{\max} = \frac{1}{\sqrt{4C_{D,0}K}} \quad [5.24]$$

Effect of weight on T_R

- Drag

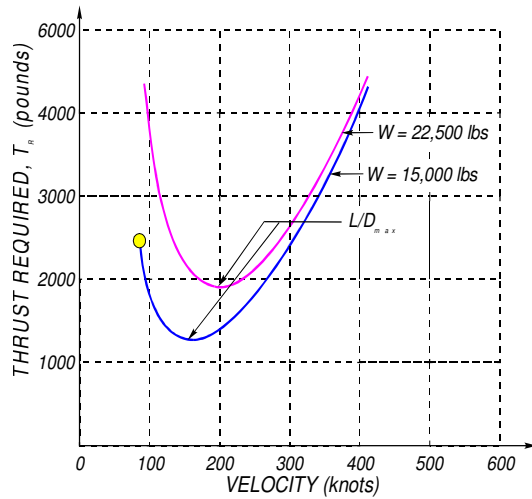
$$D = \frac{C_{D_0} \rho V^2 S}{2} + \frac{2W^2}{\rho V^2 S \pi e A R}$$

- Increasing aircraft weight by ΔW

$$D = \frac{C_{D_0} \rho V^2 S}{2} + \frac{2(W + \Delta W)^2}{\rho V^2 S \pi e A R}$$

- Then

$$D = \frac{C_{D_0} \rho V^2 S}{2} + \frac{2W^2}{\rho V^2 S \pi e A R} + \frac{2(2W\Delta W + \Delta W^2)}{\rho V^2 S \pi e A R}$$

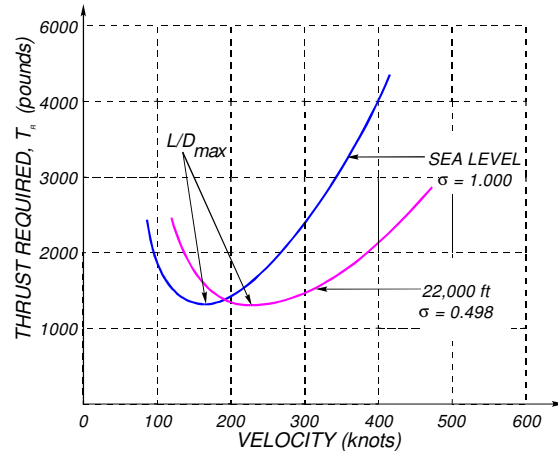


Effect of altitude on T_R

- Multiplying the drag equation by ρ/ρ

$$D = \frac{C_{D_0} \rho_0 V^2 S}{2} + \frac{2W^2}{\rho_0 V^2 S \pi e A R}$$

- Does not change $T_{R \min}$
- Minimum drag occurs at a higher V_∞
- T_R curve opens up and shifts to the right

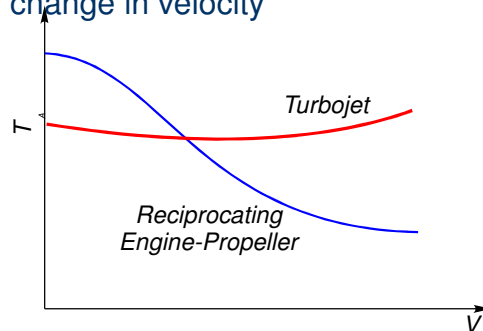


Thrust Available

- Thrust required is dictated by the airframe
 - Shape (airfoil, planform, fuselage, empennage)
 - Size (surface area, frontal area, airfoil)
 - Configuration (clean, gear down, flaps down)
- Thrust available is dictated by the powerplant (engine type, prop)
 - Reciprocating engine-propeller combination
 - Turbojet
 - Turboprop (turbine engine and propeller)
 - Turbofan
 - Ducted propeller
 - Rocket

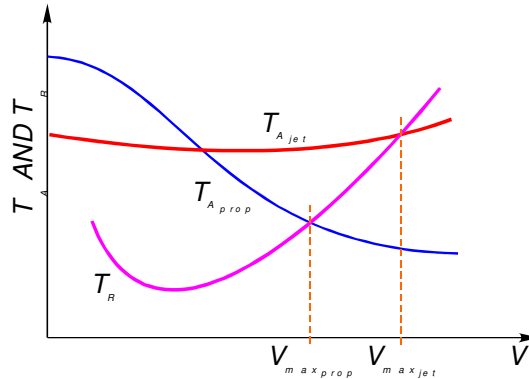
Thrust Available

- Accelerating a mass of air gives T_A
 - Propeller operates on a large volume of air and imparts a small change in velocity
 - A turbojet operates on a smaller mass of air and imparts a larger change in velocity



Thrust Available

- T_A and T_R curve intersections give V_{max}
 - This statement is true for only a single altitude, since T_A and T_R are both altitude dependent
 - T_A goes down as altitude increases



Importance of the Ratios C_L/C_D , $C_L^{3/2}/C_D$, $C_L^{1/2}/C_D$

$$\left. \frac{C_L}{C_D} \right|_{\max} \Rightarrow \begin{array}{l} \text{Max Range for reciprocating engine/propeller airplanes} \\ \text{Max Endurance for jet-propelled airplanes} \end{array}$$

$$\left. \frac{C_L^{3/2}}{C_D} \right|_{\max} \Rightarrow \text{Max Endurance for reciprocating engine/propeller}$$

$$\left. \frac{C_L^{1/2}}{C_D} \right|_{\max} \Rightarrow \text{Max Range for jet-propelled airplanes}$$

Aerodynamic Relations Associated with Maximum C_L/C_D , $C_L^{3/2}/C_D$, and $C_L^{1/2}/C_D$

$$\frac{L}{D} = \frac{C_L}{C_D} = \frac{C_L}{C_{D,0} + KC_L^2}$$

$$\frac{d(C_L/C_D)}{dC_L} = 0 \Rightarrow C_{D,0} = KC_L^2$$

$$\left(\frac{L}{D}\right)_{\max} = \left(\frac{C_L}{C_D}\right)_{\max} = \sqrt{\frac{1}{4C_{D,0}K}}$$

$$L = W = \frac{1}{2}\rho_{\infty}V_{\infty}^2SC_L$$

$$V_{(L/D)\max} = \left(\frac{2}{\rho_{\infty}}\sqrt{\frac{KW}{C_{D,0}S}}\right)^{1/2}$$

$$\frac{C_L^{3/2}}{C_D} = \frac{C_L^{3/2}}{C_{D,0} + KC_L^2}$$

$$\frac{d(C_L^{3/2}/C_D)}{dC_L} = 0 \Rightarrow C_{D,0} = \frac{1}{3}KC_L^2$$

$$\left(\frac{C_L^{3/2}}{C_D}\right)_{\max} = \frac{1}{4}\left(\frac{3}{KC_{D,0}^{1/3}}\right)^{3/4}$$

$$V_{(C_L^{3/2}/C_D)\max} = \left(\frac{2}{\rho_{\infty}}\sqrt{\frac{KW}{3C_{D,0}S}}\right)^{1/2}$$

$$V_{(C_L^{3/2}/C_D)\max} = \left(\frac{1}{3}\right)^{1/4} V_{(L/D)\max}$$

Aerodynamic Relations Associated with Maximum C_L/C_D , $C_L^{3/2}/C_D$, and $C_L^{1/2}/C_D$

$$(C_L^{1/2}/C_D)_{\max} \Rightarrow C_{D,0} = 3KC_L^2$$

$$\left(\frac{C_L^{1/2}}{C_D}\right)_{\max} = \frac{3}{4}\left(\frac{1}{3KC_{D,0}^3}\right)^{1/4}$$

$$V_{(C_L^{1/2}/C_D)\max} = \left(\frac{2}{\rho_{\infty}}\sqrt{\frac{3KW}{C_{D,0}S}}\right)^{1/2}$$

$$V_{(C_L^{1/2}/C_D)\max} = 3^{1/4}V_{(L/D)\max}$$

$$V_{(C_L^{3/2}/C_D)\max} < V_{(C_L/C_D)\max} < V_{(C_L^{1/2}/C_D)\max}$$

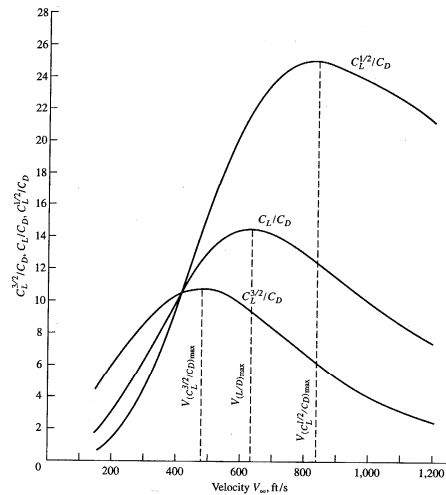


Figure 5.11 Variation of $C_L^{3/2}/C_D$, C_L/C_D , and $C_L^{1/2}/C_D$ versus velocity for the Gulfstream IV at the conditions set in Example 5.1. Altitude = 30,000 ft, $W = 73,000$ lb.