Thermocapillary Drop Motion on a Horizontal Solid Surface

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Outline

- Background
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- Objectives
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- Results and Conclusions
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Background

- • A drop when introduced on ^a horizontal solid surface will spread and attain an equilibrium shape.
- A drop on a horizontal surface can be made to move by applying forces to it.
- Forces can be created by two methods:
	- $\mathcal{L}_{\mathcal{A}}$ Wettability gradient (contact angle gradient)
	- Thermocapillarity (temperature gradient)

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Cold

Drop motion

Decane drop of radius 1.6 mm

Field of view~19 mm

Why does a drop move in a temperature gradient?

Applications

It is basically a transport mechanism for liquids without the need for a conventional mechanism

- \bullet Lab-on-a-chip.
	- \bullet **Chemistry**
	- \bullet Biotechnology

• Reduced gravity (or space) experiments.

Literature Review

Theory

• Brochard (1989)

- Developed a 2D model for small contact angles using lubrication theory, for both wettability and temperature gradients
- \bullet Ford and Nadim (1993)
	- Developed a 2D model for an arbitrarily-shaped drop using lubrication theory
	- The model allowed for the possibility of change in the contact angles due to a temperature gradient
- \bullet Subramanian *et al.* (2005)
	- Developed ^a 3D model using lubrication theory
	- The model was developed and used for wettability gradients

Experiments employing temperature gradients

- Bouasse (1924) performed experiments with an oil drop on a slightly tilted metal wire. The drop moved up when the lower end of the wire was heated.
- Brzoska et al. (1993) studied the motion of silicone oil drops on silanized surfaces.
- Yarin *et al.* (2002) studied the motion of drops of different alkanes along a glass fiber.
- Chen *et al.* (2005) performed experiments with various alkanes on silanized surfaces.

Objectives

- \bullet • To measure the velocities of liquid drops of various sizes at different gradients.
- \bullet • To measure the <u>contact angle</u> as a function of temperature .
- \bullet • To <u>extend</u> the theoretical model developed by Subramanian *et al.* (2005) for temperature gradients.
- \bullet • To compare the measured velocities with predictions from theory.

Schematic of the experimental apparatus

Hardware and software

Thermal gradient block

Surface Preparation

- A glass surface is cleaned with deionized water, acetone and methanol.
- The surface is then washed with base Piranha (30:70; $\mathsf{NH}_4\mathsf{OH}$: $\mathsf{H}_2\mathsf{O}_2$) solution.
- Next the surface is coated with PGMA using ^a spin coating method.
- Then ^a PDMS layer is adhered onto the PGMA layer on the glass surface.

Experimental procedure

- A steady state temperature gradient is established using circulating fluid from constant temperature baths
- The coated glass slide is then placed on the block surface and sufficient time is allowed for ^a steady gradient to be established on the surface
- Next, decane drops of different sizes are introduced on different tracks on the surface and their motion is monitored using video cameras.
- The captured images are then tracked using SPOTLIGHT which yields position vs. time data.
- The instantaneous velocity is deduced by finding the slope of the position vs. time curve.

Theoretical model

$$
\frac{\partial p}{\partial x} = \mu \frac{\partial^2 v_x}{\partial z^2}
$$

$$
v_x(z=0)=-U
$$

$$
\left. \mu \frac{\partial v_x}{\partial z} \right|_{z=h} = \frac{\partial \gamma}{\partial x}
$$

$$
v_x = -U + \frac{1}{2\mu} \frac{\partial p}{\partial x} \left(z^2 - 2hz \right) + \frac{z}{\mu} \frac{\partial \gamma}{\partial x}
$$

$$
\int_{0}^{h} v_x dz = 0
$$
 Volumetric flow condition

$$
\tau_w = -\mu \frac{\partial v_x}{\partial z}\bigg|_{z=0} = -\frac{3\mu U}{h} + \frac{1}{2} \frac{\partial \gamma}{\partial x}
$$

$$
h = \sqrt{R^2 \csc^2 \theta - r^2} - R \cot \theta
$$

$$
F_h = \int_{\Omega} \tau_w \, dA
$$

$$
F_{h} = -6\pi\mu UR\left[g\left(\theta,1-\varepsilon\right)-g\left(\theta,0\right)\right]+\frac{\pi R^{2}G\gamma_{T}}{2}
$$

where

$$
g = \int \frac{r dr}{\sqrt{cosec^2 \theta - r^2} - \cot \theta} = -\left[\cot \theta \ln \left(\sqrt{cosec^2 \theta - r^2} - \cot \theta\right)\right]
$$

$$
+\sqrt{\csc^2\theta-r^2}-\cot\theta\bigg]
$$
 and

$$
\varepsilon = L_{\rm s}/R
$$

Force at the contact line

 $dF_{cl} = \left[\left(\gamma_{SG} - \gamma_{SL} \right)_f - \left(\gamma_{SG} - \gamma_{SL} \right)_r \right] \cos \phi \ dl$

$$
F_{cl} = 2R \int_{0}^{\frac{\pi}{2}} \left\{ \left(\gamma_{SG} - \gamma_{SL} \right)_f - \left(\gamma_{SG} - \gamma_{SL} \right)_r \right\} \cos \phi \, d\phi
$$

$$
\gamma_{SG} - \gamma_{SL} = \gamma \cos \theta_e
$$

$$
\gamma = \gamma_0 + \gamma_T G x
$$

where G is the temperature gradient

$$
F_{cl} = 4R^2 G \gamma_T \cos \theta_e \int_0^{\frac{\pi}{2}} \cos^2 \phi \, d\phi = \pi R^2 G \gamma_T \cos \theta_e
$$

$$
F_{h} + F_{cl} = -6\pi\mu UR\left[g\left(\theta, 1-\varepsilon\right)-g\left(\theta, 0\right)\right]
$$

$$
+ \frac{\pi R^2 G \gamma_T}{2} + \pi R^2 G \gamma_T \cos \theta_e = 0
$$

$$
U = \frac{RG\gamma_T (1 + 2\cos\theta_e)}{12\mu \left[g\left(\theta, 1 - \varepsilon\right) - g\left(\theta, 0\right)\right]}
$$
(5.51)

Decane Results

Contact angle measurements

High Gradient. . . **.** . . . **.** . . . **. 12 R = 1.53 mm 10 G = 2.77 K/mm**Position x (mm) **Position x (mm) 8 642 0** 20 **0 2 4 6 8 10 12 14 16 18 20**

Time t (seconds)

Velocity vs position High gradient

Corrected velocity of a drop

Comparison with predictions

Predicted vs observed slopes

High gradient

Aspect ratio

Capillary number is ^a dimensionless quantity that represents the relative effect of viscousforces to surface tensionforces, and is written as

 $Ca = \frac{\mu U}{\sigma}$

Aspect ratio =

 γ

AB

A

D

CD

Hexadecane Results

Theory vs experiments

Slopes comparison

Squalane Results

High gradient

Slopes comparison

Aspect ratio of squalane

Conclusions

Decane

- The contact angle of decane increases with increasing temperature.
- The velocity of ^a drop scales approximately linearly with size in the range of the data collected.
- The velocity appears to decrease with increasing viscosity.
- The slopes of the prediction are reasonable considering the approximations in developing the theory.
- The slopes of the predictions were found to be very sensitive to contact angle.
- Drop below ^a critical size did not move. This indicates the possible existence of contact angle hysteresis.

Hexadecane

• Hexadecane drops are larger than the decane drops, so that their shape is influenced significantly by gravity.

- The velocity of hexadecane drops also scales approximately linearly with radius.
- Velocity appears to decrease with increasing viscosity.
- Observed velocities are much smaller than thosepredicted. The reasons are not obvious.

• There is clear evidence of a critical radius belowwhich ^a drop does not move in ^a given temperature gradient.

Squalane

• In order to exceed the critical radius, large drops had to be used; gravity plays ^a significant role in deforming the shapes of these drops

•the footprints of squalane drops are well-deformed from ^a circle, and the aspect ratio changes during the motion of the drop

•The velocity of squalane drops increases as the viscosity increases

•The velocity of squalane drops scales approximately linearly with the average radius

• The predictions are much worse than in the other cases; this may be connected to the extreme deformation of the footprints of the drops.

Recommendations

- Low contact angles should be measured with ^a better technique.
- The predictions for hexadecane and squalane were very different from experimental data. It would be interesting to study those liquids, particularly squalane in detail.

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Questions?